

On Flow-Aware CSMA

in Multi-Channel Wireless Networks

Mathieu Feuillet

Joint work with Thomas Bonald

CISS 2011

Outline

Model

Background

Standard CSMA

Flow-aware CSMA

Conclusion

Outline

Model

Background

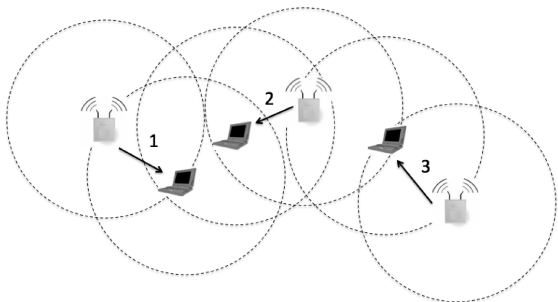
Standard CSMA

Flow-aware CSMA

Conclusion

Conflict graphs

The network is represented by a set of conflict graphs, **one per channel**.



Channel 1

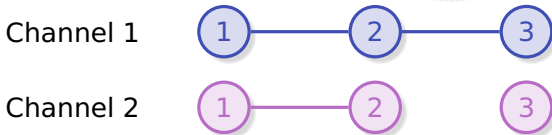
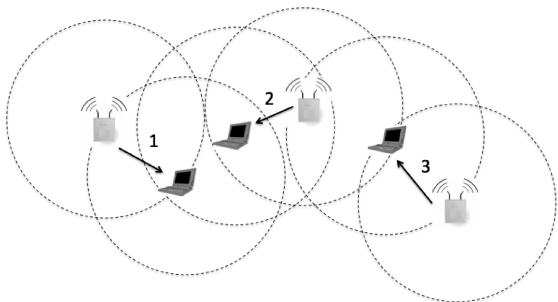


Channel 2



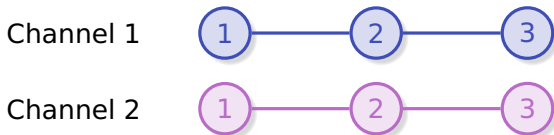
Conflict graphs

The network is represented by a set of conflict graphs, **one per channel**.



Conflict graphs on different channels can be different.

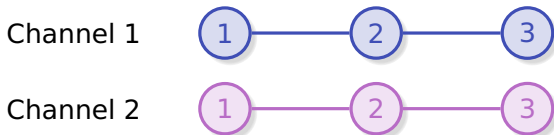
Conflict graphs



Schedules:

- ▶ $\emptyset, \{(1, 1)\}, \{(2, 1)\}, \{(3, 1)\}, \{(1, 1), (3, 1)\}$.

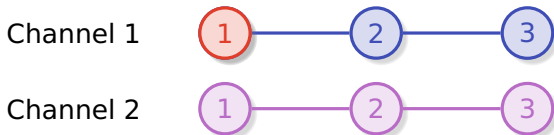
Conflict graphs



Schedules:

- ▶ \emptyset , $\{(1, 1)\}$, $\{(2, 1)\}$, $\{(3, 1)\}$, $\{(1, 1), (3, 1)\}$.

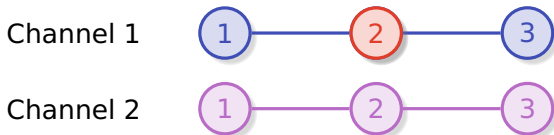
Conflict graphs



Schedules:

- ▶ \emptyset , $\{(1, 1)\}$, $\{(2, 1)\}$, $\{(3, 1)\}$, $\{(1, 1), (3, 1)\}$.

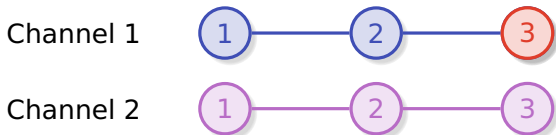
Conflict graphs



Schedules:

- ▶ \emptyset , $\{(1, 1)\}$, $\{(2, 1)\}$, $\{(3, 1)\}$, $\{(1, 1), (3, 1)\}$.

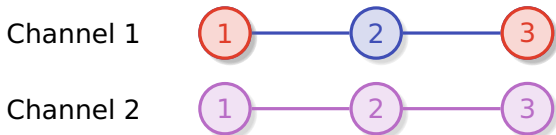
Conflict graphs



Schedules:

- ▶ \emptyset , $\{(1, 1)\}$, $\{(2, 1)\}$, $\{(3, 1)\}$, $\{(1, 1), (3, 1)\}$.

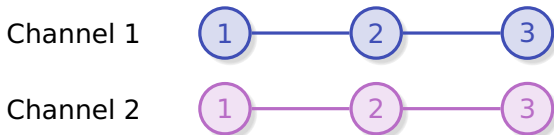
Conflict graphs



Schedules:

- ▶ $\emptyset, \{(1, 1)\}, \{(2, 1)\}, \{(3, 1)\}, \{(1, 1), (3, 1)\}$.

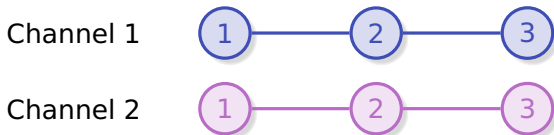
Conflict graphs



Schedules:

- ▶ \emptyset , $\{(1, 1)\}$, $\{(2, 1)\}$, $\{(3, 1)\}$, $\{(1, 1), (3, 1)\}$.
- ▶ $\{(1, 2)\}$, $\{(2, 2)\}$, $\{(3, 2)\}$, $\{(1, 2), (3, 2)\}$.

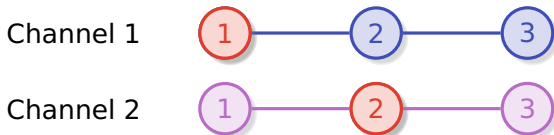
Conflict graphs



Schedules:

- ▶ $\emptyset, \{(1, 1)\}, \{(2, 1)\}, \{(3, 1)\}, \{(1, 1), (3, 1)\}$.
- ▶ $\{(1, 2)\}, \{(2, 2)\}, \{(3, 2)\}, \{(1, 2), (3, 2)\}$.
- ▶ $\{(1, 1), (2, 2)\}, \{(1, 2), (2, 1), (3, 1)\}, \dots$

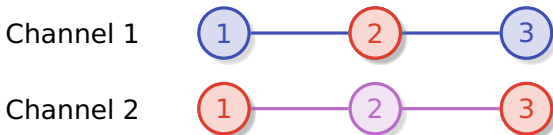
Conflict graphs



Schedules:

- ▶ $\emptyset, \{(1, 1)\}, \{(2, 1)\}, \{(3, 1)\}, \{(1, 1), (3, 1)\}$.
- ▶ $\{(1, 2)\}, \{(2, 2)\}, \{(3, 2)\}, \{(1, 2), (3, 2)\}$.
- ▶ $\{(1, 1), (2, 2)\}, \{(1, 2), (2, 1), (3, 1)\}, \dots$

Conflict graphs



Schedules:

- ▶ $\emptyset, \{(1, 1)\}, \{(2, 1)\}, \{(3, 1)\}, \{(1, 1), (3, 1)\}$.
- ▶ $\{(1, 2)\}, \{(2, 2)\}, \{(3, 2)\}, \{(1, 2), (3, 2)\}$.
- ▶ $\{(1, 1), (2, 2)\}, \{(1, 2), (2, 1), (3, 1)\}, \dots$

Time-scale separation

We assume time-scale separation between flow-level and packet-level dynamics.

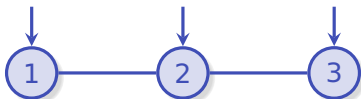
- ▶ At the packet level, the number of flows is fixed.
- ▶ At the flow level, the packet-level dynamics are at equilibrium: the throughput of each node is the fraction of time it is active.

Time-scale separation

We assume time-scale separation between flow-level and packet-level dynamics.

- ▶ At the packet level, the number of flows is fixed.
- ▶ At the flow level, the packet-level dynamics are at equilibrium: the throughput of each node is the fraction of time it is active.

Example:



$$\phi_1 = \rho_{\{1\}} + \rho_{\{1,3\}}, \quad \phi_2 = \rho_{\{2\}}, \quad \phi_3 = \rho_{\{3\}} + \rho_{\{1,3\}}.$$

Capacity Region

Defined as the set of all feasible link throughputs

$$\phi_k = \sum_{i:k \in S_i} p_i$$

Throughput of node k

Schedule i

Probability of schedule i

The diagram illustrates the equation $\phi_k = \sum_{i:k \in S_i} p_i$. Three arrows point from labels below to terms in the equation: one from 'Throughput of node k ' to ϕ_k , one from 'Schedule i ' to S_i , and one from 'Probability of schedule i ' to p_i .

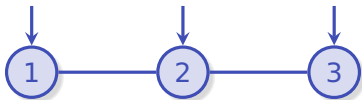
Capacity Region

Defined as the set of all feasible link throughputs

$$\phi_k = \sum_{i:k \in S_i} p_i$$

Throughput of node k Schedule i Probability of schedule i

Example:



Schedules: \emptyset , $\{1\}$, $\{2\}$, $\{3\}$, $\{1, 3\}$.

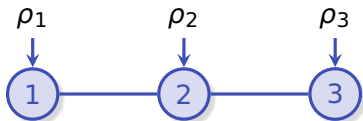
Capacity region: $\{\phi_1 + \phi_2 \leq 1, \phi_2 + \phi_3 \leq 1\}$.

Stability region

Defined as the set of traffic intensities such that the network is stable.

$$\rho_k = \lambda_k \times \sigma_k$$

Example:



The stability region depends on the algorithm.

Stability region

Defined as the set of traffic intensities such that the network is stable.

$$\rho_k = \lambda_k \times \sigma_k$$



Flows arrival rate

Stability region

Defined as the set of traffic intensities such that the network is stable.

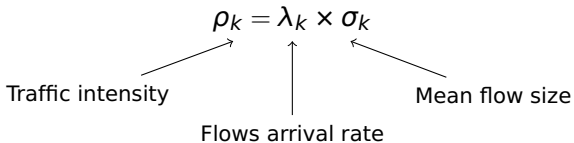
$$\rho_k = \lambda_k \times \sigma_k$$

Flows arrival rate

Mean flow size

Stability region

Defined as the set of traffic intensities such that the network is stable.



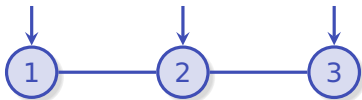
Optimal stability region

The stability region of any algorithm is included in the capacity region. The interior of the capacity region is called the optimal stability region.

Optimal stability region

The stability region of any algorithm is included in the capacity region. The interior of the capacity region is called the optimal stability region.

Example:



Optimal stability region:

$$\{\rho_1 + \rho_2 < 1, \rho_2 + \rho_3 < 1\}.$$

Outline

Model

Background

Standard CSMA

Flow-aware CSMA

Conclusion

Maximal Weight scheduling

Tassiulas & Ephremides 92

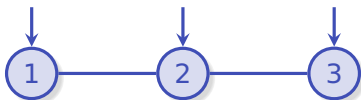
$$\max w_i(x) = \sum_{k \in S_i} x_k$$

Maximal Weight scheduling

Tassiulas & Ephremides 92

$$\max w_i(x) = \sum_{k \in S_i} x_k$$

Example:



$x_1 + x_3 > x_2 \Rightarrow$ schedule $\{1, 3\}$

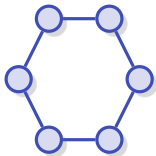
$x_1 + x_3 < x_2 \Rightarrow$ schedule $\{2\}$

Suboptimal algorithms

Maximal queue scheduling

Mc Keown 95

$\max x_k$



Dimakis & Walrand 06

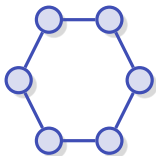
Efficiency $\frac{8}{9} \approx 0.89$

Suboptimal algorithms

Maximal queue scheduling

Mc Keown 95

$\max x_k$



Dimakis & Walrand 06

Efficiency $\frac{8}{9} \approx 0.89$

Maximal size scheduling

Charporkar, Kar &
Sarkar 95

$\max |S_j|$



Bonald & Massoulié 01

Efficiency ≈ 0.76

Optimal Algorithms

Adaptive rate-based CSMA Jiang & Walrand 08

- ▶ Measure the packet input and output rates and adapt the back-off accordingly.
- ▶ Learning algorithm.

Optimal Algorithms

Adaptative rate-based CSMA

Jiang & Walrand 08

- ▶ Measure the packet input and output rates and adapt the back-off accordingly.
- ▶ Learning algorithm.

Adaptative queue based CSMA

Rajagopalan, Shah & Shin 09

- ▶ Adapt the back-off according to the $\log \log$ of the queue length.
- ▶ Some technical assumptions.

Outline

Model

Background

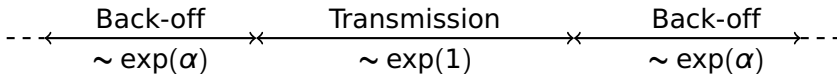
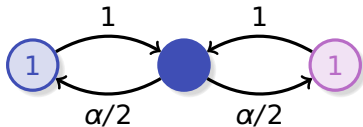
Standard CSMA

Flow-aware CSMA

Conclusion

Standard CSMA

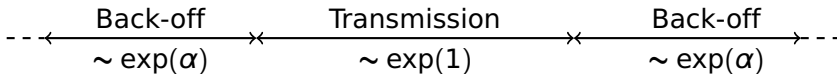
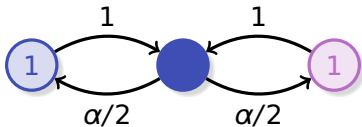
Probe a channel **at random**, after some random backoff time.



$$\phi_1(x) = \frac{\alpha}{1 + \alpha}$$

Standard CSMA

Probe a channel **at random**, after some random backoff time.



$$\phi_1(x) = \frac{\alpha}{1 + \alpha}$$

$$\text{Stability region: } \left\{ \rho_1 < \frac{\alpha}{1 + \alpha} \right\} \xrightarrow{\alpha \rightarrow \infty} \{ \rho_1 < 1 \}$$

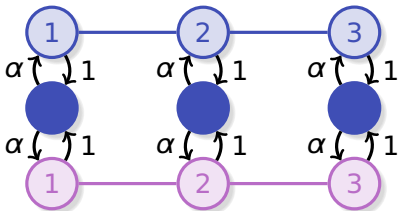
Standard CSMA

$$w_i(x) = \prod_{(k,j) \in S_i} \alpha_{k,j} \mathbb{1}_{\{x_k > 0\}}$$

Weight of schedule i

Ratio of transmission time to
virtual backoff time at link k
on channel j

Example: Assume $\alpha_{k,j} = \alpha$ for $k = 1, 2, 3$ and $j = 1, 2$.



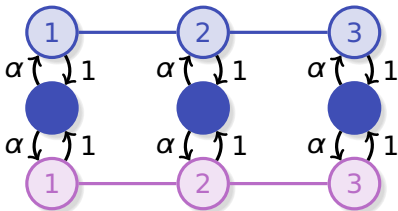
Standard CSMA

$$w_i(x) = \prod_{(k,j) \in S_i} \alpha_{k,j} \mathbb{1}_{\{x_k > 0\}}$$

Weight of schedule i

Ratio of transmission time to
virtual backoff time at link k
on channel j

Example: Assume $\alpha_{k,j} = \alpha$ for $k = 1, 2, 3$ and $j = 1, 2$.



$$\emptyset: w_i(x) = 1$$

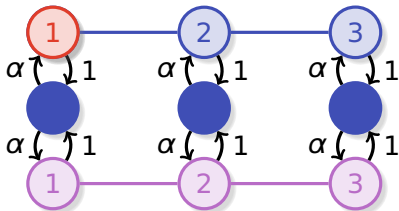
Standard CSMA

$$w_i(x) = \prod_{(k,j) \in S_i} \alpha_{k,j} \mathbb{1}_{\{x_k > 0\}}$$

Weight of schedule i

Ratio of transmission time to virtual backoff time at link k on channel j

Example: Assume $\alpha_{k,j} = \alpha$ for $k = 1, 2, 3$ and $j = 1, 2$.



$$\{(1, 1)\} : w_i(x) = \alpha$$

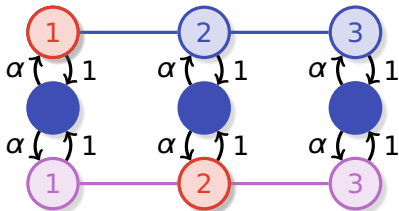
Standard CSMA

$$w_i(x) = \prod_{(k,j) \in S_i} \alpha_{k,j} \mathbb{1}_{\{x_k > 0\}}$$

Weight of schedule i

Ratio of transmission time to virtual backoff time at link k on channel j

Example: Assume $\alpha_{k,j} = \alpha$ for $k = 1, 2, 3$ and $j = 1, 2$.



$$\{(1, 1), (2, 2)\} : w_i(x) = \alpha^2$$

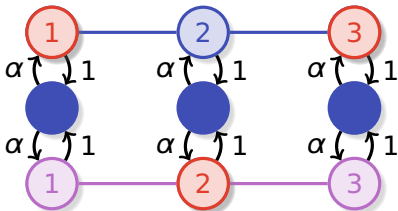
Standard CSMA

$$w_i(x) = \prod_{(k,j) \in S_i} \alpha_{k,j} \mathbb{1}_{\{x_k > 0\}}$$

↑
Weight of schedule i

←
Ratio of transmission time to
virtual backoff time at link k
on channel j

Example: Assume $\alpha_{k,j} = \alpha$ for $k = 1, 2, 3$ and $j = 1, 2$.



$$\{(1, 1), (2, 2), (3, 1)\} : w_i(x) = \alpha^3$$

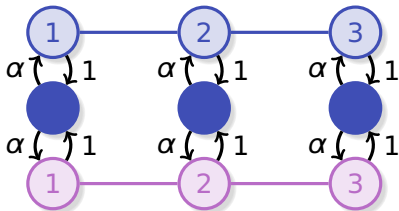
Standard CSMA

$$w_i(x) = \prod_{(k,j) \in S_i} \alpha_{k,j} \mathbb{1}_{\{x_k > 0\}}$$

Weight of schedule i

Ratio of transmission time to virtual backoff time at link k on channel j

Example: Assume $\alpha_{k,j} = \alpha$ for $k = 1, 2, 3$ and $j = 1, 2$.



$$w_i(x) = \alpha^n \text{ for } n \text{ active links}$$

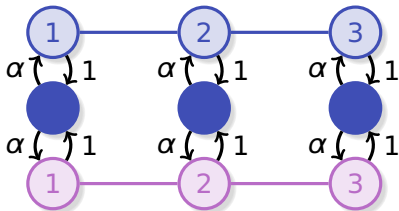
Standard CSMA

$$\phi_k(x) = \sum_{i:k \in S_i} p_i(x)$$

Throughput of link k ←

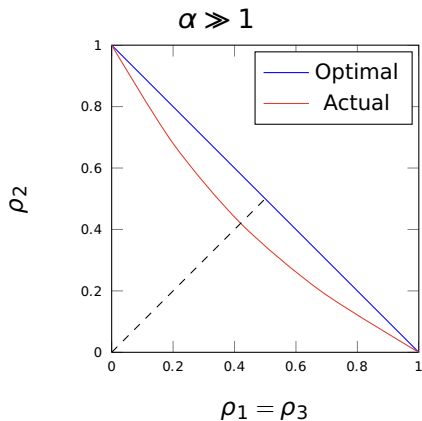
← Probability of schedule i

Example: Assume $\alpha_{k,j} = \alpha$ for $k = 1, 2, 3$ and $j = 1, 2$.



$$\phi_1(x) = \phi_3(x) = \frac{2\alpha + 6\alpha^2 + 2\alpha^3}{1 + 6\alpha + 8\alpha^2 + 2\alpha^3}, \quad \phi_2(x) = \frac{2\alpha + 4\alpha^2 + 2\alpha^3}{1 + 6\alpha + 8\alpha^2 + 2\alpha^3}$$

Suboptimality of standard CSMA 1 channel



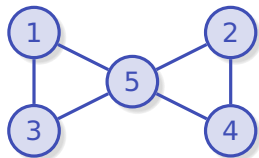
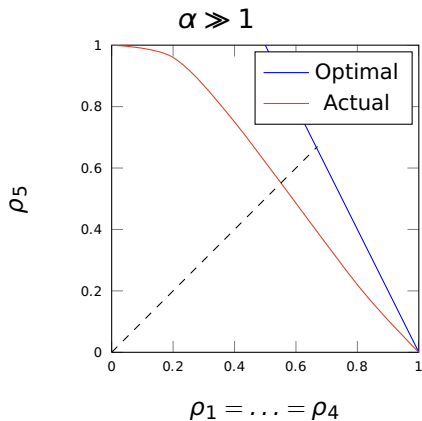
Homogeneous case

$$\rho_1 = \rho_2 = \rho_3$$

Efficiency ≈ 0.84 .

Suboptimality of standard CSMA

2 channels



Homogeneous case

$$\rho_1 = \dots = \rho_5$$

Efficiency ≈ 0.85

Outline

Model

Background

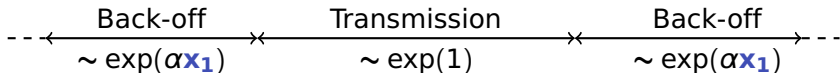
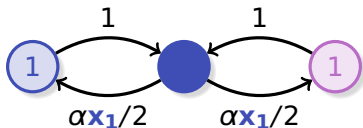
Standard CSMA

Flow-aware CSMA

Conclusion

Flow-aware CSMA

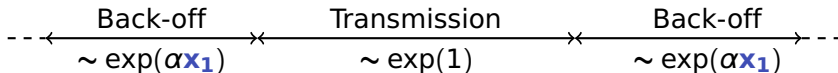
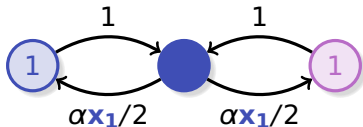
Proposed modification of CSMA:
Exponential backoff time for each flow



$$\phi_1(x) = \frac{\alpha \mathbf{x}_1}{1 + \alpha \mathbf{x}_1}$$

Flow-aware CSMA

Proposed modification of CSMA:
Exponential backoff time for each flow



$$\phi_1(x) = \frac{\alpha x_1}{1 + \alpha x_1}$$

Stability region: $\{\rho_1 < 1\}$

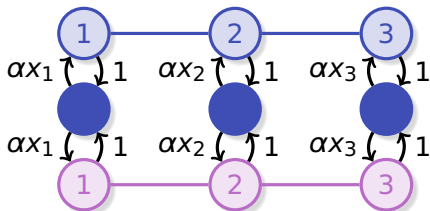
Flow-aware CSMA

$$w_i(x) = \prod_{k \in S_i} \alpha_{k,j} x_k$$

Weight of schedule i

Ratio of transmission time to virtual back-off time at link k on channel j

Example: Assume $\alpha_{k,j} = \alpha$ for $k = 1, 2, 3$ and $j = 1, 2$.



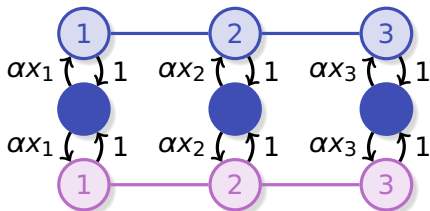
Flow-aware CSMA

$$w_i(x) = \prod_{k \in S_i} \alpha_{k,j} x_k$$

Weight of schedule i

Ratio of transmission time to virtual back-off time at link k on channel j

Example: Assume $\alpha_{k,j} = \alpha$ for $k = 1, 2, 3$ and $j = 1, 2$.



$$\emptyset: w_i(x) = 1$$

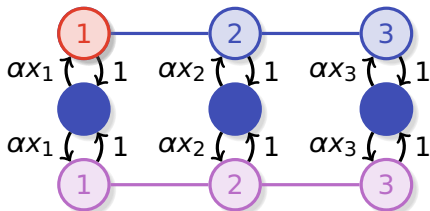
Flow-aware CSMA

$$w_i(x) = \prod_{k \in S_i} \alpha_{k,j} x_k$$

Weight of schedule i

Ratio of transmission time to virtual back-off time at link k on channel j

Example: Assume $\alpha_{k,j} = \alpha$ for $k = 1, 2, 3$ and $j = 1, 2$.



$$\{(1, 1)\} : w_i(x) = \alpha x_1$$

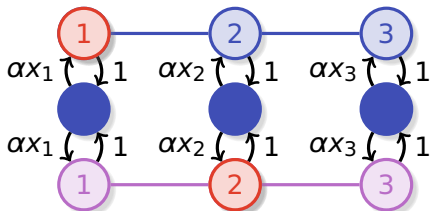
Flow-aware CSMA

$$w_i(x) = \prod_{k \in S_i} \alpha_{k,j} x_k$$

Weight of schedule i

Ratio of transmission time to virtual back-off time at link k on channel j

Example: Assume $\alpha_{k,j} = \alpha$ for $k = 1, 2, 3$ and $j = 1, 2$.



$$\{(1, 1), (2, 2)\} : w_i(x) = \alpha^2 x_1 x_2$$

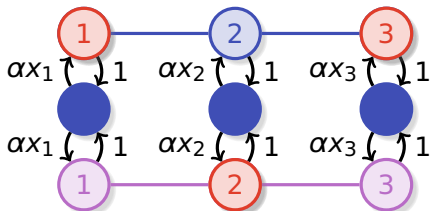
Flow-aware CSMA

$$w_i(x) = \prod_{k \in S_i} \alpha_{k,j} x_k$$

Weight of schedule i

Ratio of transmission time to virtual back-off time at link k on channel j

Example: Assume $\alpha_{k,j} = \alpha$ for $k = 1, 2, 3$ and $j = 1, 2$.



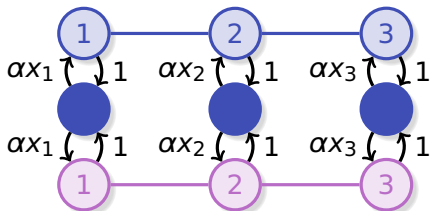
$$\{(1, 1), (2, 2), (3, 1)\} : w_i(x) = \alpha^3 x_1 x_2 x_3$$

Flow-aware CSMA

$$\phi_k(x) = \sum_{i:k \in S_i} p_i(x)$$

Throughput of link k Probability of schedule i

Example: Assume $\alpha_{k,j} = \alpha$ for $k = 1, 2, 3$ and $j = 1, 2$.



$$\phi_2(x) \propto 2\alpha^3 x_1 x_2 x_3 + 2\alpha^2 x_2 (x_1 + x_3) + 2\alpha x_2$$

Optimality of flow-aware CSMA

Theorem

*The flow-aware CSMA algorithm is optimal: for **any** number of channels and **any** sets of conflicts graphs, it stabilizes the network for all traffic intensities inside the capacity region.*

Sketch of proof:

- ▶ When the number of flows is high, the algorithm behaves as **max-weight**: the algorithm selects schedules of high weight with high probability.
- ▶ Proof based on Foster's criterion.

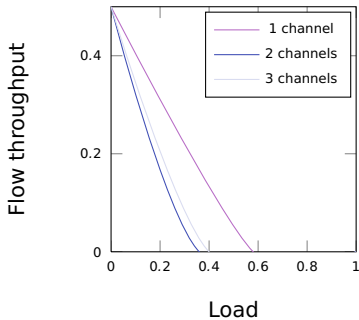
Throughput performance



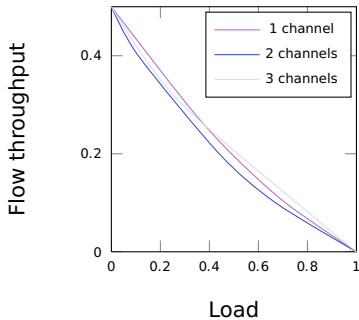
Homogeneous load

$$\alpha = 1$$

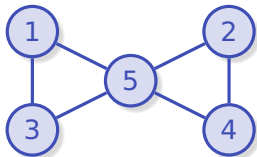
Standard CSMA



Flow-aware CSMA



Time-scale separation

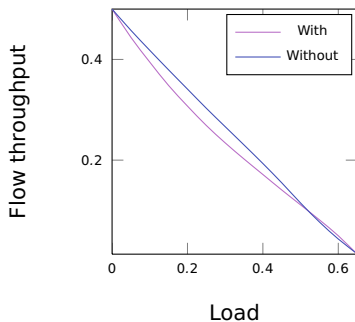
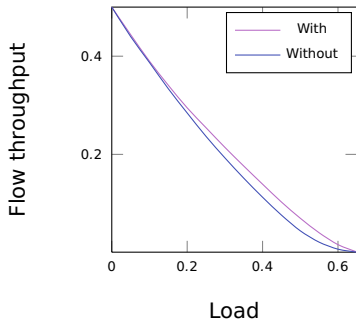


Center link

$$\alpha = 1$$

1 packet per flow

Edge link



Outline

Model

Background

Standard CSMA

Flow-aware CSMA

Conclusion

Conclusion

A simple, distributed, asynchronous access scheme that is provably optimal.

A theoretical issue:

- ▶ Time-scale separation

Extensions of the model:

- ▶ Collisions
- ▶ Throughput performance